



TANGO
Device
Server

Modbus User's Guide

Modbus Class

Revision: - Author: peru
Implemented in C++ - CVS repository: ESRF

Introduction:

A Class to handle the modbus protocol over TCP/IP or Serial (RTU).

Class Inheritance:

- Tango::Device_4Impl
 - Modbus

Class Description:

This device is intended to drive a RF switch interfaced by a Wago module.

Properties:

Device Properties		
Property name	Property type	Description
Serialline	Tango::DEV_STRING	Name of the serial line (for RTU protocol)
Address	Tango::DEV_SHORT	Node index (for RTU protocol when several controllers are chained by a serial line)
Protocol	Tango::DEV_STRING	RTU'' : Binary serial communication. ''TCP'' : Communication over ethernet.
Iphost	Tango::DEV_STRING	Host IP address (for TCP protocol)

Device Properties Default Values:

Property Name	Default Values
Serialline	No default value
Address	No default value
Protocol	No default value
Iphost	No default value

There is no Class properties.

Commands:

More Details on commands....

Device Commands for Operator Level		
Command name	Argument In	Argument Out
Init	DEV_VOID	DEV_VOID
State	DEV_VOID	DEV_STATE
Status	DEV_VOID	CONST_DEV_STRING
ForceSingleCoil	DEVVAR_SHORTARRAY	DEV_VOID
ReadCoilStatus	DEV_SHORT	DEV_SHORT
ReadInputStatus	DEVVAR_SHORTARRAY	DEVVAR_CHARARRAY
ReadHoldingRegisters	DEVVAR_SHORTARRAY	DEVVAR_SHORTARRAY
ReadInputRegisters	DEVVAR_SHORTARRAY	DEVVAR_SHORTARRAY
PresetSingleRegister	DEVVAR_SHORTARRAY	DEV_VOID
ReadExceptionStatus	DEV_VOID	DEV_SHORT
FetchCommEventCtr	DEV_VOID	DEVVAR_SHORTARRAY
ForceMultipleCoils	DEVVAR_SHORTARRAY	DEV_VOID
PresetMultipleRegisters	DEVVAR_SHORTARRAY	DEV_VOID
MaskWriteRegister	DEVVAR_SHORTARRAY	DEV_VOID
ReadWriteRegister	DEVVAR_SHORTARRAY	DEVVAR_SHORTARRAY

1 - Init

- Description:** This commands re-initialise a device keeping the same network connection.
 After an Init command executed on a device, it is not necessary for client to re-connect to the device.
 This command first calls the device *delete_device()* method and then execute its *init_device()* method.
 For C++ device server, all the memory allocated in the *nit_device()* method must be freed in the *delete_device()* method.
 The language device desctructor automatically calls the *delete_device()* method.
- Argin:**
DEV_VOID : none.
- Argout:**
DEV_VOID : none.
- Command allowed for:**

2 - State

- **Description:** This command gets the device state (stored in its *device_state* data member) and returns it to the caller.
- **Argin:**
DEV_VOID : none.
- **Argout:**
DEV_STATE : State Code
- **Command allowed for:**

3 - Status

- **Description:** This command gets the device status (stored in its *device_status* data member) and returns it to the caller.
- **Argin:**
DEV_VOID : none.
- **Argout:**
CONST_DEV_STRING : Status description
- **Command allowed for:**

4 - ForceSingleCoil

- **Description:** Write single coil (digital I/O) state.
- **Argin:**
DEVVAR_SHORTARRAY : coil address, 0/1
- **Argout:**
DEV_VOID :
- **Command allowed for:**

5 - ReadCoilStatus

- **Description:** Read coil (digital I/O) status.
- **Argin:**
DEV_SHORT : coil address
- **Argout:**

DEV_SHORT : Coil status

- **Command allowed for:**

6 - ReadInputStatus

- **Description:** Read discrete input status. Return one boolean per array element.
- **Argin:**
DEVVAR_SHORTARRAY : input address, no. of inputs
- **Argout:**
DEVVAR_CHARARRAY : Input status.
- **Command allowed for:**

7 - ReadHoldingRegisters

- **Description:** Read multiple 16bits registers.
- **Argin:**
DEVVAR_SHORTARRAY : register address, no. of registers
- **Argout:**
DEVVAR_SHORTARRAY : Holding 16bits register.
- **Command allowed for:**

8 - ReadInputRegisters

- **Description:** Read Multiple 16bits input registers.
- **Argin:**
DEVVAR_SHORTARRAY : register address, no. of registers
- **Argout:**
DEVVAR_SHORTARRAY : Input 16bits registers
- **Command allowed for:**

9 - PresetSingleRegister

- **Description:** Write single 16bits register.
- **Argin:**
DEVVAR_SHORTARRAY : Register address, register value.
- **Argout:**
DEV_VOID :
- **Command allowed for:**

10 - ReadExceptionStatus

- **Description:** Read exception status (usually a predefined range of 8 bits)
- **Argin:**
DEV_VOID :
- **Argout:**
DEV_SHORT : exception status
- **Command allowed for:**

11 - FetchCommEventCtr

- **Description:** Fetch communications event counter.
- **Argin:**
DEV_VOID :
- **Argout:**
DEVVAR_SHORTARRAY : status, event count
- **Command allowed for:**

12 - ForceMultipleCoils

- **Description:** Write multiple coils (digital I/O) state. argin[0] = coil_address argin[1] = number of coils argin[2] = 1st coil state argin[3] = 2nd coil state ...
- **Argin:**
DEVVAR_SHORTARRAY : coil address, nb of coils, coil states
- **Argout:**
DEV_VOID :

- **Command allowed for:**

13 - PresetMultipleRegisters

- **Description:** Write multiple 16bits registers. argin[0] = register address argin[1] = number of registers argin[2] = 1st register argin[3] = 2nd register ...
- **Argin:**
DEVVAR_SHORTARRAY : register address, nb of registers, register data
- **Argout:**
DEV_VOID :
- **Command allowed for:**

14 - MaskWriteRegister

- **Description:** Mask write a 16bits register.
- **Argin:**
DEVVAR_SHORTARRAY : register address, AND mask, OR mask
- **Argout:**
DEV_VOID :
- **Command allowed for:**

15 - ReadWriteRegister

- **Description:** Read and Write multiple 16bits registers. argin[0] = read address argin[1] = nb of registers to read argin[2] = write address, argin[3] = nb of registers to write, argin[4] = 1st register value to write argin[5] = 2nd register value to write ...
- **Argin:**
DEVVAR_SHORTARRAY : read address, no. to read, write address, nb.of write, write data
- **Argout:**
DEVVAR_SHORTARRAY : read registers
- **Command allowed for:**

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