









TANGO Device Server

Bumper powersupply User's Guide

Bumper Class

Revision: Bumper-Release_1_0 - Author: bourtemb Implemented in C++ - CVS repository: ESRF

Introduction:

The bumper powersupplies are pulsed powersupplies. They are used to deviate the beam from the booster into the transfer line 2.

Class Inheritance:

- Tango::DeviceImpl
 - PowerSupply
 - Bumper

Properties:

| Device Properties | | | | |
|------------------------|-------------------|---|--|--|
| Property name | Property type | Description | | |
| Din_device | Tango::DEV_STRING | Name of the device used to get the state of the powersupply. | | |
| Adc_device | Tango::DEV_STRING | Name of the ADC device used to read the voltage. | | |
| Dac_device | Tango::DEV_STRING | Name of the DAC device used to set the voltage on the powersupply. | | |
| Min_authorised_current | Tango::DEV_DOUBLE | Minimum current in Amps authorised. If the user tries to a current value below this minimum authorised, the minimum authorised current will be set on the powersupp | | |
| OffVref | Tango::DEV_DOUBLE | The Voltage applied on the dac will be computed as follow Vref = OffVref + LinVref * CurrentSetValue | | |
| LinVref | Tango::DEV_DOUBLE | The Voltage applied on the dac will be computed as follow Vref = OffVref + LinVref * CurrentSetValue | | |
| Channel | Tango::DEV_USHORT | Bumper power supply channel B1 => channel = 1 B2 => channel = 2 B3 => channel = 3 | | |
| Dout_device | Tango::DEV_STRING | Name of the device used to change the state of the powersupply. The server will send ON, OFF and RESET commands to the powersupply via this device. | | |

Device Properties Default Values:

| Property Name | Default Values | | |
|------------------------|-----------------------|--|--|
| Din_device | No default value | | |
| Adc_device | No default value | | |
| Dac_device | No default value | | |
| Min_authorised_current | 70.0 | | |
| OffVref | 0.0 | | |
| LinVref | 0.01 | | |
| Channel | 1 | | |
| Dout_device | No default value | | |

There is no Class properties.

States:

| States | | |
|---------|---|--|
| Names | Descriptions | |
| FAULT | The device is in FAULT state when an error is detected, after the power up of the powersupply and after a change from LOCAL to REMOTE mode. | |
| OFF | No pulse in the magnet | |
| ON | Normal mode of operation (Pulse sent to the magnet) | |
| DISABLE | This state corresponds to the LOCAL mode. Entered by a switch on the front panel of the powersupply | |
| ALARM | An attribute is in alarm. For example when the read and set values are too much different. | |
| UNKNOWN | There is a communication problem with the IO, ADC or DAC board. | |

Attributes:

| Scalar Attributes | | | | | |
|--|------------|------------|--------|--|--|
| Attribute name | Data Type | R/W Type | Expert | | |
| Current: The powersupply current setting in amps | DEV_DOUBLE | READ_WRITE | No | | |
| Voltage: The powersupply voltage in volts. | DEV_DOUBLE | READ_WRITE | Yes | | |
| CurrentSetPoint : The current set value as stored in the powersupply. | DEV_DOUBLE | READ | No | | |

Commands:

More Details on commands....

| Device Commands for Operator Level | | | | | |
|------------------------------------|-------------|------------------|--|--|--|
| Command name | Argument In | Argument Out | | | |
| Init | DEV_VOID | DEV_VOID | | | |
| State | DEV_VOID | DEV_STATE | | | |
| Status | DEV_VOID | CONST_DEV_STRING | | | |
| On | DEV_VOID | DEV_VOID | | | |
| Off | DEV_VOID | DEV_VOID | | | |
| Reset | DEV_VOID | DEV_VOID | | | |

1 - Init

O Description: This commands re-initialise a device keeping the same network connection. After an Init command executed on a device, it is not necessary for client to re-connect to the device. This command first calls the device delete_device() method and then execute its init_device() method. For C++ device server, all the memory allocated in the nit_device() method must be freed in the delete_device() method.

The language device desctructor automatically calls the *delete_device()* method.

O Argin:

DEV_VOID: none.

○ Argout:

DEV_VOID: none.

- O Command allowed for:
 - Tango::FAULT
 - Tango::OFF
 - Tango::ON
 - Tango::DISABLE
 - Tango::ALARM
 - Tango::UNKNOWN

2 - State

- O **Description:** This command gets the device state (stored in its *device_state* data member) and returns it to the caller.
- Argin:

DEV_VOID: none.

○ Argout:

DEV_STATE: State Code

- O Command allowed for:
 - Tango::FAULT
 - Tango::OFF
 - Tango::ON
 - Tango::DISABLE
 - Tango::ALARM
 - Tango::UNKNOWN

3 - Status

- O **Description:** This command gets the device status (stored in its *device_status* data member) and returns it to the caller.
- O Argin:

DEV_VOID: none.

O Argout:

CONST_DEV_STRING: Status description

- Command allowed for:
 - Tango::FAULT
 - Tango::OFF
 - Tango::ON
 - Tango::DISABLE
 - Tango::ALARM
 - Tango::UNKNOWN

4 - On

- O **Description:** Switch powersupply ON.
- O Argin:

 $DEV_VOID:$

O Argout:

 $DEV_VOID:$

- Command allowed for:
 - Tango::OFF
 - Tango::ON
 - Tango::ALARM
 - Tango::UNKNOWN

5 - Off

- O **Description:** Switch powersupply OFF.
- O Argin:

DEV_VOID:

○ Argout: **DEV_VOID**:

○ Command allowed for:

Tango::OFFTango::ON

Tango::ALARMTango::UNKNOWN

6 - Reset

- **Description:** Reset the powersupply to a well known state.
- O Argin:

DEV_VOID:

○ Argout: **DEV_VOID**:

○ Command allowed for:

Tango::FAULTTango::ON

Tango::ALARMTango::UNKNOWN

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